

1 Definitions and Notation

A graph $G = (V, E)$ is an ordered pair of *vertices* $V = \{v_1, v_2, \dots, v_{|V|}\}$ and *edges* E . Here, we only consider *undirected graphs without loops*, i.e., $E \subseteq \{\{v, w\} : v, w \in V, v \neq w\}$. Two vertices v and w are called *connected* in case there exists a path between them. A graph is called *connected* in case any pair of vertices (v, w) is connected. For a subset V' of the vertex set V , we refer to $G^{V'} = (V', E')$, $E' := \{\{v, w\} \in E : v, w \in V'\}$ as the V' -induced subgraph of G .

As the k -*Neighborhood* $N_k(e)$ of an edge $e = \{a, b\}$, we denote the set of all $(k - 2)$ -tuples of vertices $v \in V, a \neq v \neq b$ that are connected to vertices a or b in the induced subgraph. We call each element $N \in N_k(e)$ a *neighbor set* of e . Each of them corresponds to the subgraph $G^{\{a, b\} \cup N}$ of G that contains a and b as well as $k - 2$ other vertices.

For a graph G , its *adjacency matrix* $A(G) = A_{i,j}$ is an $n \times n$ matrix defined as follows:

$$A_{ij}^u = \begin{cases} 1 \text{ (true)} & \text{if } i > j \wedge \{v_i, v_j\} \in E \\ 0 \text{ (false)} & \text{if } i > j \wedge \{v_i, v_j\} \notin E \\ \text{undefined} & \text{otherwise} \end{cases}$$

We denote the *set of all adjacency matrices* of size k as \mathcal{A}_k , $|\mathcal{A}_k| = 2^{\frac{n \cdot (n-1)}{2}}$. The set of the adjacency matrices of *connected graphs* of size k is denoted as $\mathcal{A}_k^{con} \subset \mathcal{A}_k$. As examples consider the following adjacency matrices:

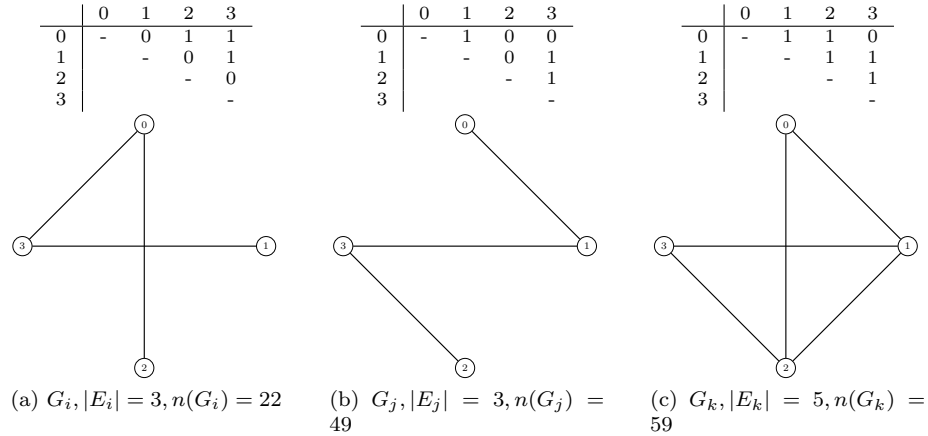


Figure 1: Examples of connected 4-vertex graphs

Assume a to be the sequence of all defined entries of an adjacency matrix A , i.e., $a = (a_1, a_2, \dots, a_{\frac{k \cdot (k-1)}{2}}) := (A_{1,2}, A_{1,3}, \dots, A_{k-1,k})$. Then, we define the *key* of an adjacency matrix A and the corresponding graph G as follows:

$$n(A) = n(G) := \sum_{i=1}^{\frac{k \cdot (k-1)}{2}} a_i \cdot 2^{i-1}$$

Then, $\mathcal{N}_k^{con} \subset [0, 2^{\frac{k \cdot (k-1)}{2}}]$ denotes the set of all keys of connected graphs of size k .

As a dynamic graph, we consider a graph whose set of edges E changes over time. We assume that in each time step, a single edge is either added to or removed from E . This change is denoted as an update: either $add(e)$ or $rm(e)$. A graph is transformed from G_i to G_{i+1} by the application of update u_{i+1} .

add example of graph transformation over time...

2 Motifs

As motifs of size k , also called k -vertex motifs or k -motifs, we consider the equivalence classes of isomorph connected k -vertex graphs which we denote as \mathcal{M}_k .

Therefore, each connected adjacency matrix $A \in \mathcal{A}_k^{con}$ is element of exactly one equivalence class represented by a motif $m \in \mathcal{M}_k$. We express this property as a function that maps the key $n(A)$ of a connected adjacency matrix A to a motif $m \in \mathcal{M}_k$, i.e.,

$$r : \mathcal{N}_k^{con} \rightarrow \mathcal{M}_k$$

This assignment can be computed by enumerating all connected adjacency matrices and determining their equivalence class by performing an isomorphism check with all existing motifs.

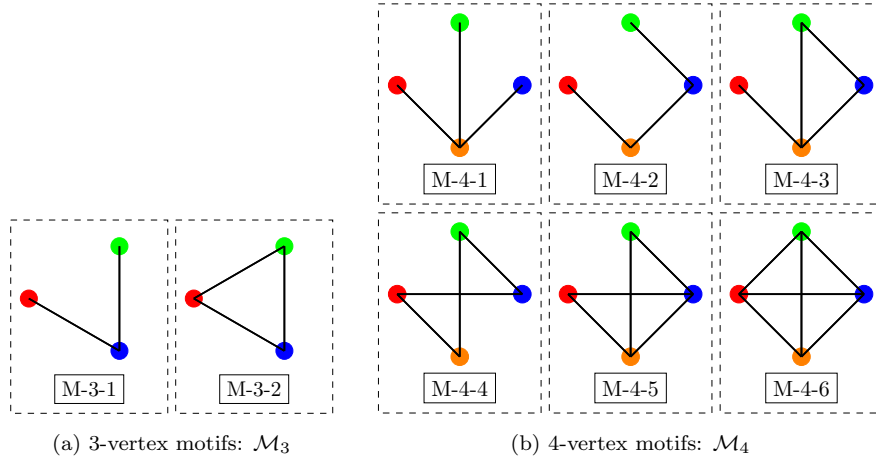


Figure 2: Examples for the set of motifs \mathcal{M}_k for different sizes

3 Implementation

For simplicity, we store the function r as integer pairs (n, m) where n is the key of a connected adjacency matrix and m the index of the equivalence class, or motif, it belongs to.

4 Algorithm

Whenever an edge $e = \{a, b\}$ is added to or removed from a graph G_i , each subgraph $G_i^{\{a, b\} \cup N}$, $N \in N_k(e)$ represents a motif that is created, transformed, or dissolved.

In case $u_i = rm(e)$, $n(A_i^{\{a, b\} \cup N})$ is the key of the adjacency matrix for $N \in N_k(e)$ before the removal. After the removal, the key will be $n(A_{i+1}^{\{a, b\} \cup N}) = n(A_i^{\{a, b\} \cup N}) - 1$, i.e., the same adjacencies except for the missing edge between the first two vertices. If $n(A_i^{\{a, b\} \cup N}) - 1 \notin \mathcal{N}_k^{con}$, the existing motif will be dissolved and is transformed otherwise.

Similarly, in case e is added to the graph G_i , $n(A_{i+1}^{\{a, b\} \cup N}) = n(A_i^{\{a, b\} \cup N}) + 1$ is the key of the adjacency matrix for the neighbor set $N \in N(a, b)$ afterwards. If $n(A_i^{\{a, b\} \cup N}) \notin \mathcal{N}_k^{con}$, a new motif is created and an existing one transformed otherwise.

From this, we can define an algorithm that updates the motif frequency \mathcal{F} for the application of an update u_i . In addition, all changes to motifs in the graph can be listed:

5 Complexity of Algorithm

When processing an update u_{i+1} , i.e., $add(\{a, b\})$ or $rm(\{a, b\})$, we must iterate over all elements of $N_k(a, b)$ with $|N_k(a, b)| \leq d_{max}^{k-2}$. Processing each neighborhood $N \in N_k(a, b)$ can be done in $O(1)$ as it only requires the generation of the key $n(A^{\{a, b\} \cup N})$, its lookup in the pre-computed assignment r , and the adaptation of \mathcal{F} . Therefore, the complexity for the execution of the algorithms is $O(d_{max}^{k-2})$.

define d_{max}
here?!?

6 Statistics about motifs

Data: $G_i, e = \{a, b\}, type \in \{add, rm\}, print \in \{true, false\}$

```

begin
  for  $N \in N_k(e)$  do
     $n_i = n(A_i^{\{a,b\} \cup N})$  ; /* key before */
    if  $type = add$  then
      |  $n_{i+1} = n_i + 1$  ; /* key after addition */
    else
      |  $n_{i+1} = n_i - 1$  ; /* key after removal */
    if  $n_i \in \mathcal{N}_k^{con}$  then
      |  $\mathcal{F}(r(n_i)) - = 1$  ; /* decr old motif */
    if  $n_{i+1} \in \mathcal{N}_k^{con}$  then
      |  $\mathcal{F}(r(n_{i+1})) + = 1$  ; /* incr new motif */
    if  $print$  then
      if  $n_i \in \mathcal{N}_k^{con} \wedge n_{i+1} \in \mathcal{N}_k^{con}$  then
        | print 'transformed: a, b, N ( $r(n_i) \rightarrow r(n_{i+1})$ )'
      else if  $n_i \in \mathcal{N}_k^{con}$  then
        | print 'dissolved: a, b, N ( $r(n_i)$ )'
      else
        | print 'created: a, b, N ( $r(n_{i+1})$ )'
    end
  end
end

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Algorithm 1: $StreaM_k$ for maintaining \mathcal{F} in dynamic graphs

k	2	3	4	5	6	7
$ \mathcal{A}_k $	2	8	64	1,024	32,768	2,097,152
$ \mathcal{A}_k^{con} $	1	4	38	827	26,704	1,866,256
$ \mathcal{M}_k $	1	2	6	21	112	853

Table 1: Statistics about adjacency matrices and motifs of different sizes